

EC axial fan

sickle-shaped blades (S series)

with round full nozzle

ebm-papst Mulfingen GmbH & Co. KG

Bachmühle 2 · D-74673 Mulfingen

Phone +49 7938 81-0

Fax +49 7938 81-110

sales@fansco.com

www.fansco.com

Limited partnership · Headquarters Mulfingen

Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen

Amtsgericht (court of registration) Stuttgart · HRB 590142

Nominal data

Type	W3G990-IC12-05	
Motor	M3G200-QA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min ⁻¹	1030
Power consumption	W	6300
Current draw	A	9.8
Max. back pressure	Pa	255
Max. back pressure	in. wg	1.02
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	40	38.7	09 Power consumption P_{ed}	kW	6.33
02 Measurement category		A		09 Air flow q_v	m ³ /h	33460
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	263
04 Efficiency grade N		41.3	40	10 Speed (rpm) n	min ⁻¹	1030
05 Variable speed drive		Yes		11 Specific ratio*		1.00

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = $1 + p_g / 100\,000\text{ Pa}$

LU-176101



Technical description

Weight	132 kg
Size	990 mm
Motor size	200
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Die-cast aluminum
Support ring material	Steel, coated with black plastic (RAL 9005)
Fan housing material	Sheet steel, galvanized and coated with black plastic (RAL 9005)
Number of blades	5
Blade pitch	0°
Airflow direction	V
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H2
Max. permitted ambient temp. for motor (transport/storage)	+ 80 °C
Min. permitted ambient temp. for motor (transport/storage)	Transport -40°C/storage -60 °C
Installation position	Shaft horizontal or rotor on bottom
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE

W3G990-IC12-05

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Approval

UL 1004-7 + 60730-1; CSA C22.2 No. 77 + CAN/CSA-E60730-1; EAC

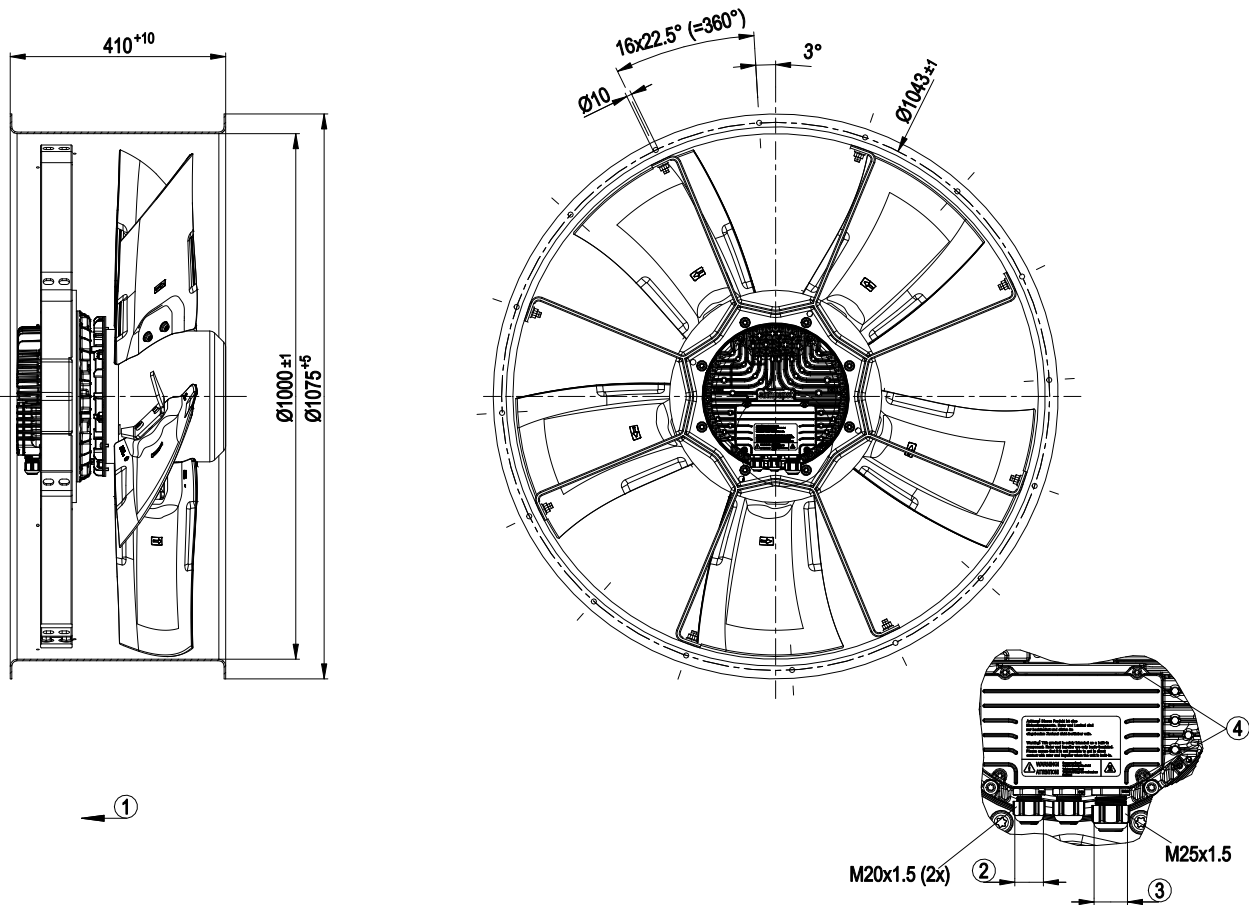


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Product drawing

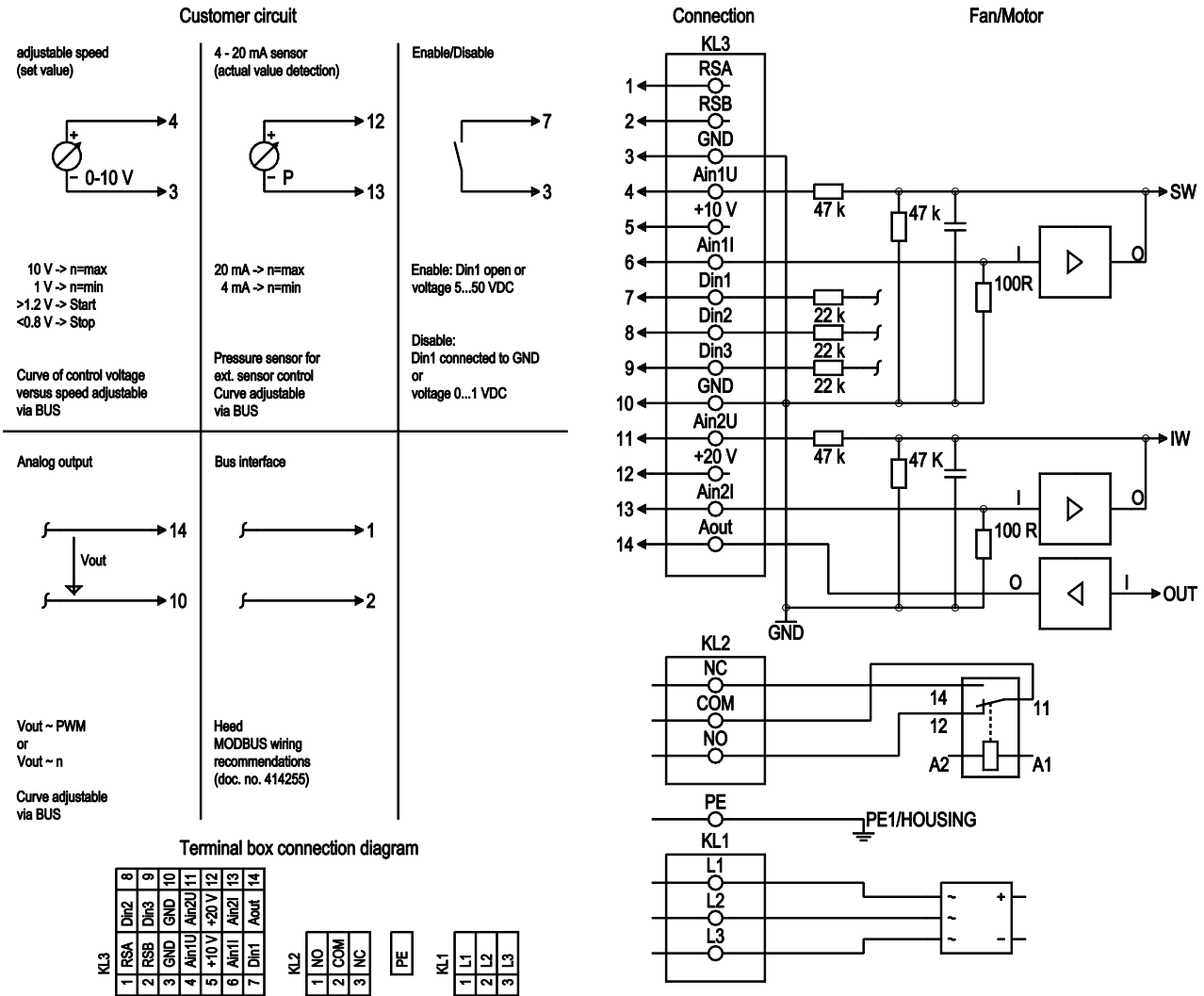


1	Direction of air flow "V"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
3	Cable diameter min. 9 mm, max. 16 mm, tightening torque 6 ± 0.9 Nm
4	Tightening torque 3.5 ± 0.5 Nm

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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply; for nominal voltage range see technical data
KL 1	2	L2	Supply connection, power supply; for nominal voltage range see technical data
KL 1	3	L3	Supply connection, power supply; for nominal voltage range see technical data
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating 250 VAC/ max. 2 A (AC1)/min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, + 10 V +/-3%, max. 10 mA, short-circuit-proof, power supply for ext. devices (e.g. potentiometers); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1 U; SELV



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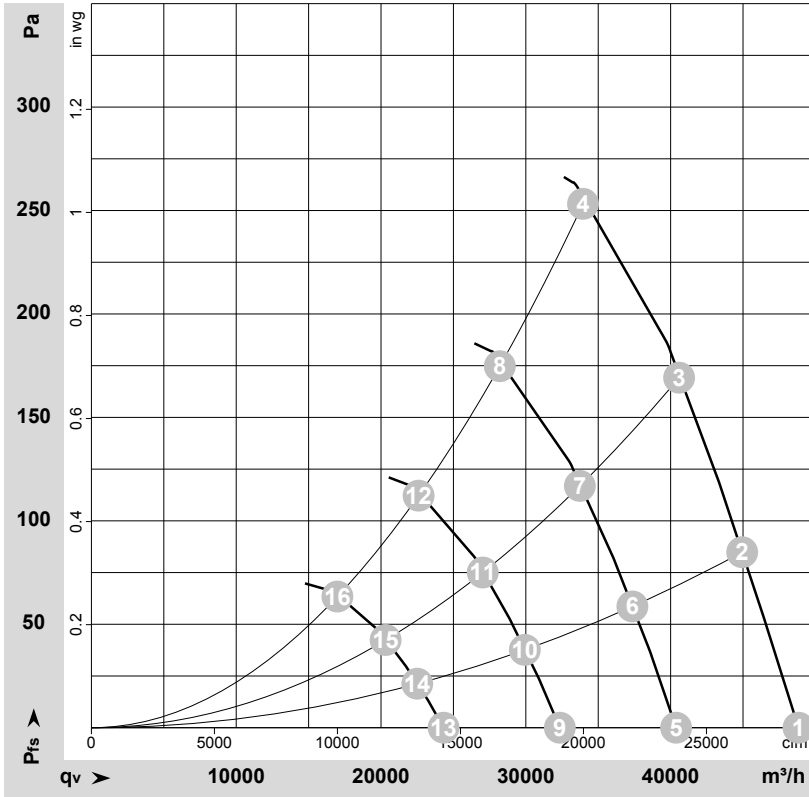
No.	Conn.	Designation	Function/assignment
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected via bus or digital input Din3; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2 I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, + 20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for ext. devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV



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Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-176101-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	400	50	1030	5653	8.71	92	101	101	48830	0	28740	0.00
2	400	50	1030	5938	9.13	91	100	100	44940	85	26450	0.34
3	400	50	1030	6227	9.56	90	99	99	40585	170	23890	0.68
4	400	50	1030	6300	9.80	92	100	100	34000	255	20010	1.02
5	400	50	855	3196	4.93	87	96	96	40380	0	23765	0.00
6	400	50	855	3411	5.25	87	95	95	37360	59	21990	0.24
7	400	50	855	3574	5.49	86	94	94	33730	118	19855	0.47
8	400	50	855	3630	5.56	87	96	96	28205	177	16600	0.71
9	400	50	685	1643	2.53	82	90	90	32350	0	19040	0.00
10	400	50	685	1754	2.70	81	90	90	29930	38	17615	0.15
11	400	50	685	1838	2.82	80	89	89	27025	76	15905	0.31
12	400	50	685	1867	2.86	82	90	90	22595	114	13300	0.46
13	400	50	515	698	1.08	74	83	83	24320	0	14315	0.00
14	400	50	515	745	1.15	74	82	82	22505	21	13245	0.08
15	400	50	515	781	1.20	73	82	81	20320	43	11960	0.17
16	400	50	515	793	1.22	75	83	83	16990	64	10000	0.26

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_v = Air flow · P_{fs} = Pressure increase

