

backward-curved, single-intake

with cube design

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Nominal data

Type	K3G900-AR10-01	
Motor	M3G200-QA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	860
Power consumption	W	7300
Current draw	A	11.2
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015			
01 Overall efficiency η_{es}	%	66.6	60.6	09 Power consumption P_{ed}	kW	7.36
02 Measurement category		A		09 Air flow q_v	m ³ /h	25650
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa	660
04 Efficiency grade N		68	62	10 Speed (rpm) n	min ⁻¹	860
05 Variable speed drive		Yes		11 Specific ratio [*]		1.01

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

^{*} Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-175421



Technical description

Weight	222 kg
Size	900 mm
Motor size	200
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Inlet nozzle material	Sheet steel, galvanized and coated with light gray plastic (RAL 7035)
Support structure material	Sheet steel, galvanized and coated with light gray plastic (RAL 7035)
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Ambient temperature note	Occasional start-up between -40°C and -25°C is permissible. For continuous operation at temperatures below -25°C (e.g. refrigeration applications) we recommend our fan design with special low-temperature bearings.
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal (base mounting only) or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection

K3G900-AR10-01

EC centrifugal module - RadiPac

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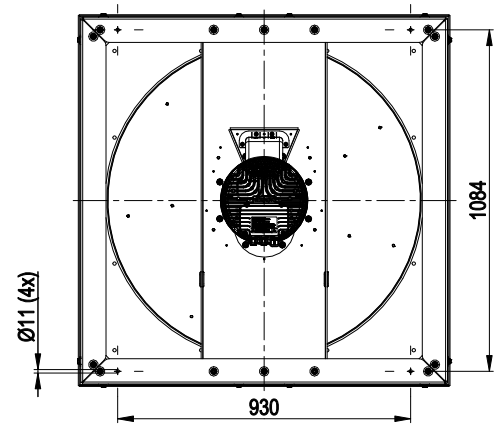
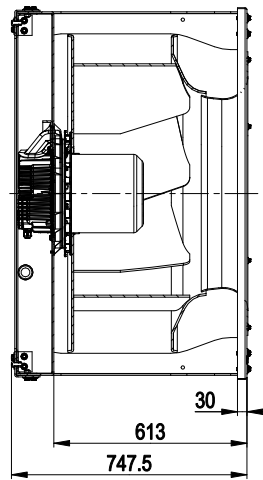
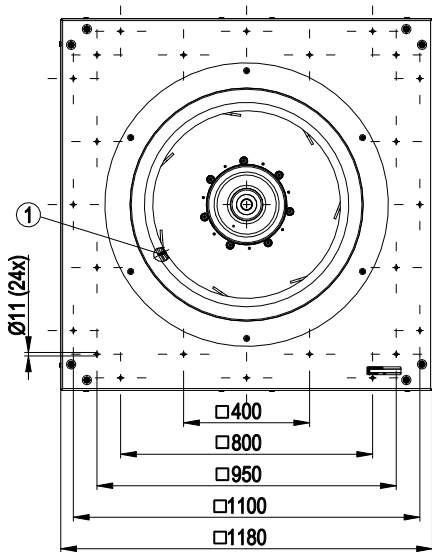
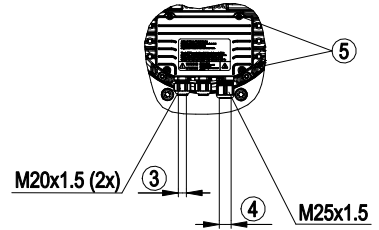
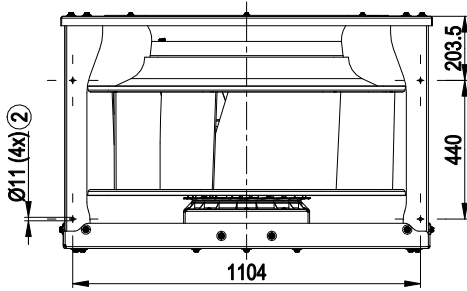
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1



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Product drawing

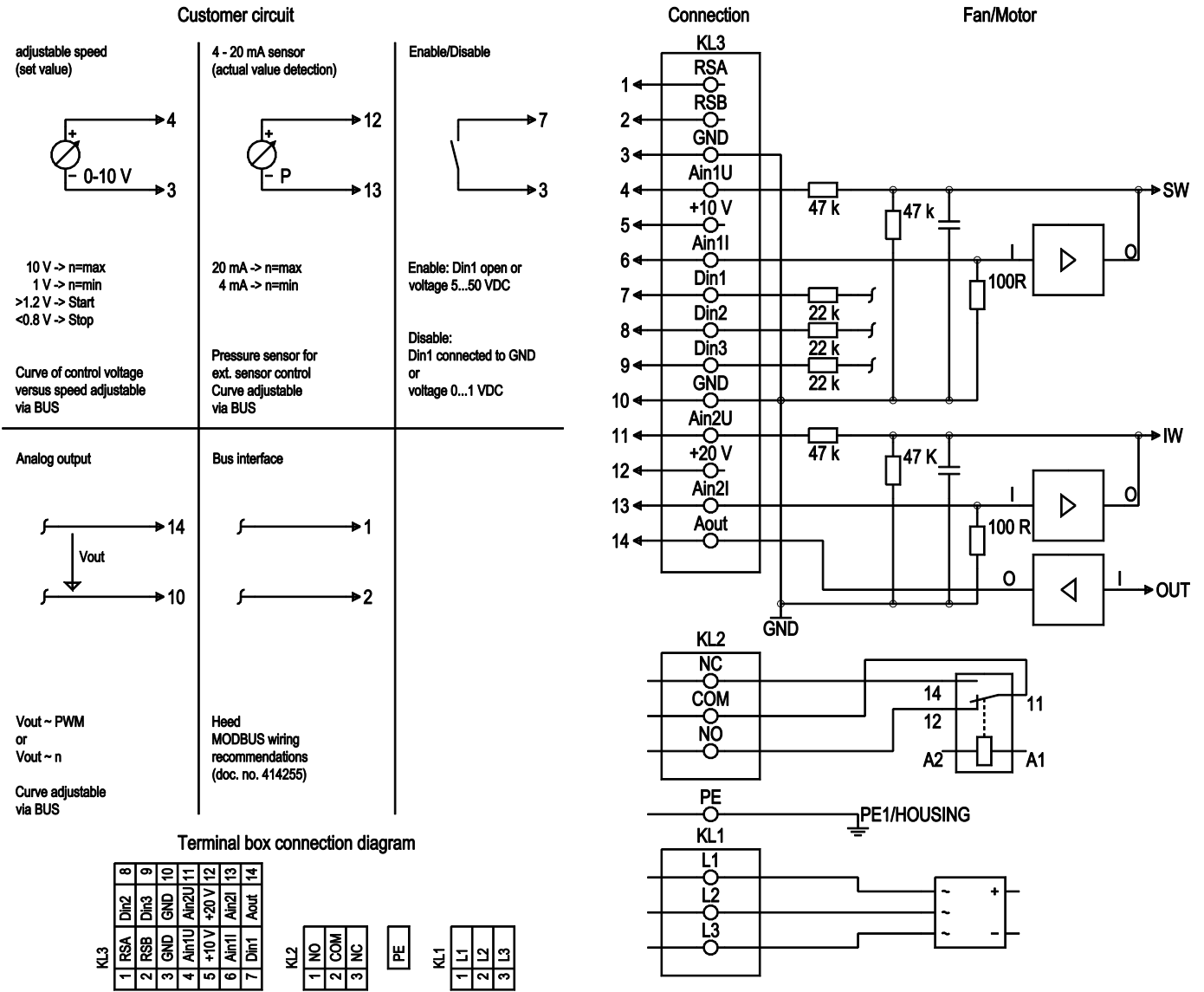


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|---|--|
| 1 | Inlet ring with pressure tap (k-factor: 900) |
| 2 | Mounting position for vibration-absorbing elements |
| 3 | Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm |
| 4 | Cable diameter min. 9 mm, max. 16 mm, tightening torque 6 ± 0.9 Nm |
| 5 | Tightening torque 3.5 ± 0.5 Nm |



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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply; for nominal voltage range see technical data
KL 1	2	L2	Supply connection, power supply; for nominal voltage range see technical data
KL 1	3	L3	Supply connection, power supply; for nominal voltage range see technical data
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating 250 VAC/ max. 2 A (AC1)/min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV



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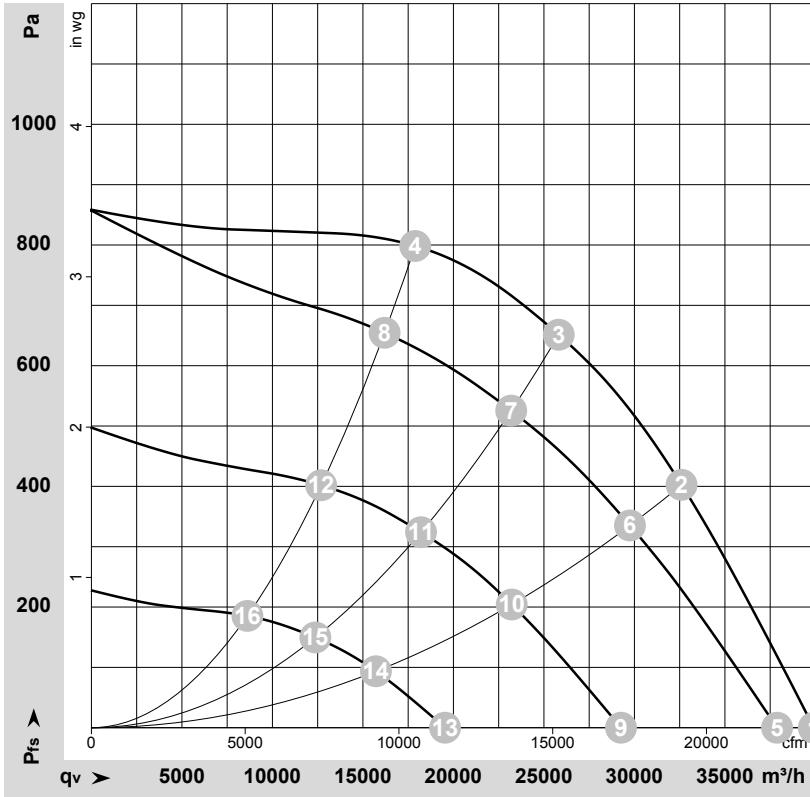
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No.	Conn.	Designation	Function/assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, + 10 V +/-3%, max. 10 mA, short-circuit-proof, power supply for ext. devices (e.g. potentiometers); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected via bus or digital input Din3; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2 I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, + 20 V +/-10%, max. 50 mA, short-circuit-proof, power supply for ext. devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV



Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-175421-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	400	50	860	4748	7.32	82	91	95	39910	0	23490	0.00
2	400	50	860	6656	10.19	76	85	89	32605	400	19190	1.61
3	400	50	860	7300	11.20	74	82	87	25820	650	15195	2.61
4	400	50	860	6805	10.41	73	81	86	17890	800	10530	3.21
5	400	50	825	4094	6.37	80	90	94	37880	0	22295	0.00
6	400	50	785	5041	7.77	74	82	87	29755	337	17515	1.35
7	400	50	775	5336	8.21	71	80	84	23195	527	13650	2.12
8	400	50	785	5049	7.78	70	79	84	16200	655	9535	2.63
9	400	50	635	1911	3.24	74	83	87	29260	0	17220	0.00
10	400	50	615	2447	3.99	67	75	80	23220	205	13665	0.82
11	400	50	610	2616	4.23	65	73	78	18210	325	10720	1.30
12	400	50	615	2446	3.99	64	72	77	12690	402	7470	1.61
13	400	50	430	667	1.52	62	72	77	19540	0	11500	0.00
14	400	50	420	846	1.80	57	65	69	15720	94	9250	0.38
15	400	50	415	905	1.89	55	64	68	12370	150	7280	0.60
16	400	50	420	843	1.80	53	62	67	8620	185	5075	0.74

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_v = Air flow · P_{fs} = Pressure increase

