

EC centrifugal fan

forward-curved, dual-intake

with housing (flange)

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Nominal data

Type	D3G180-HE09-02	
Motor	M3G084-FA	
Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	2110
Power consumption	W	750
Current draw	A	3.3
Min. back pressure	Pa	240
Min. back pressure	in. wg	0.96
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60
Starting current	A	3.1

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015		
01 Overall efficiency η_{es}	%	47.5	36.3	09 Power consumption P_{ed}	kW 0.6
02 Measurement category		A		09 Air flow q_v	m ³ /h 1405
03 Efficiency category		Static		09 Pressure increase p_{fs}	Pa 665
04 Efficiency grade N		55.2	44	10 Speed (rpm) n	min ⁻¹ 2600
05 Variable speed drive		Yes		11 Specific ratio*	1.01

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = $1 + p_g / 100\,000\text{ Pa}$

LU-169969



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Technical description

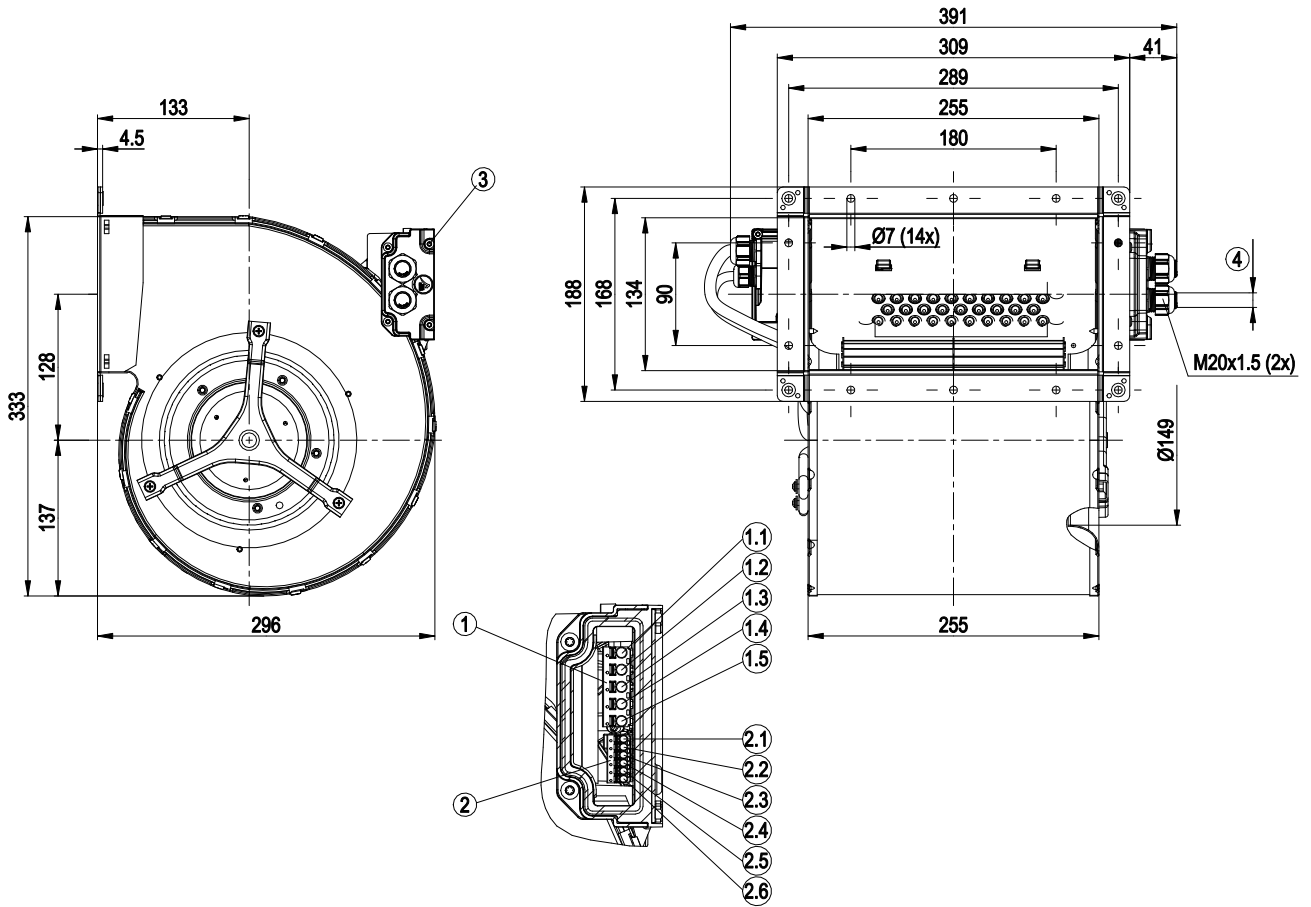
Weight	10.28 kg
Size	180 mm
Motor size	84
Rotor surface	Painted black
Impeller material	Sheet steel, galvanized
Housing material	Sheet steel, galvanized
Motor suspension	Motor mounted on brackets for one-sided vibration damping
Direction of rotation	Counterclockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+85 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	<ul style="list-style-type: none"> - Output 10 VDC, max. 10 mA - Operation and alarm display - Tach output - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, active - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal strip
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Pollution degree	2
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; EN 60335-1; CE
Approval	EAC



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Product drawing



1	Terminal 1
1.1	PE
1.2	L
1.3	N
1.4	NC
1.5	COM
2	Terminal 2
2.1	0-10 V
2.2	+10 V
2.3	GND
2.4	RSA
2.5	RSB
2.6	Tach
3	Tightening torque 3 ± 0.5 Nm
4	Cable diameter min. 6 mm, max. 10 mm, tightening torque 1.8 ± 0.3 Nm Cable diameter min. 8 mm, max. 12 mm, tightening torque 1.8 ± 0.3 Nm (use must be made of seal provided)

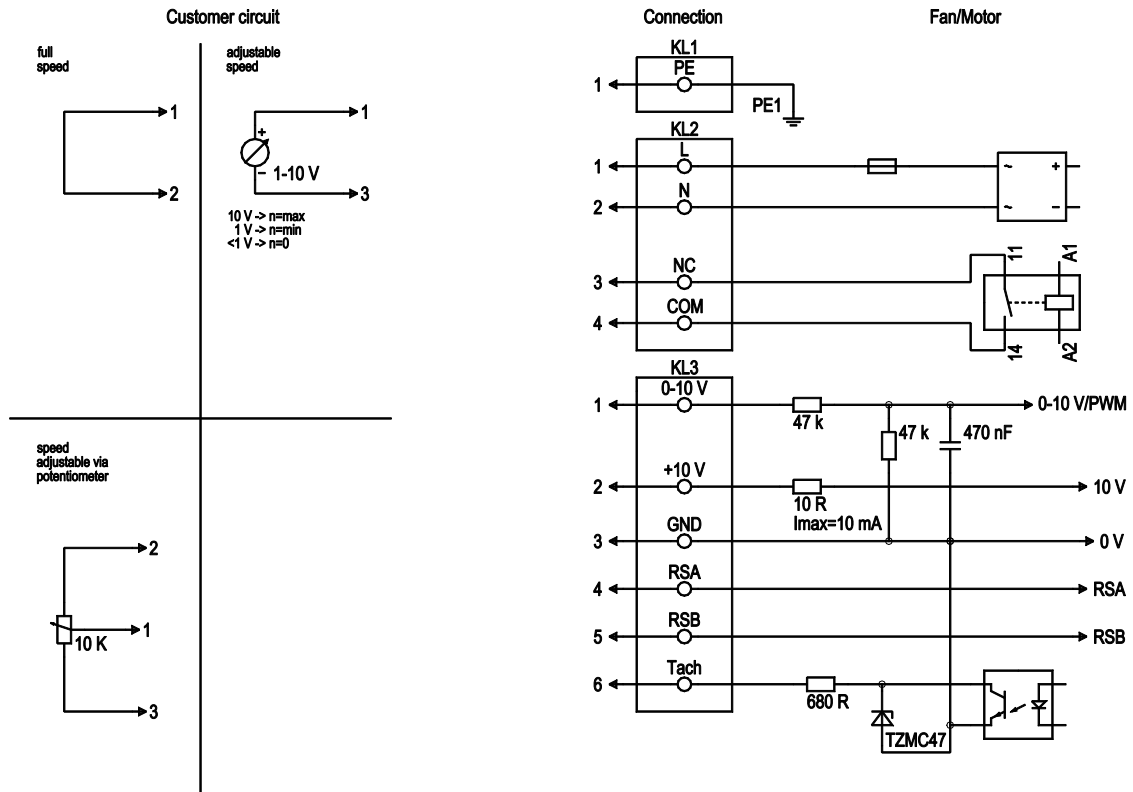


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Connection diagram



No.	Conn.	Designation	Function/assignment
KL1	1	PE	Protective earth
KL2	2	L	Power supply, phase, 50/60 Hz
KL2	3	N	Power supply, neutral conductor, 50/60 Hz
KL2	4	NC	Status relay, floating status contact, break for failure, contact rating 250 VAC/2 A (AC1) min. 10 mA, basic insulation on supply side and reinforced insulation on control interface side
KL2	5	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; basic insulation on supply side and reinforced insulation on control interface side
KL3	1	0-10 V	Analog input (set value), 0-10 V, Ri = 100 kΩ, adjustable curve, SELV
KL3	2	+10 V	Fixed voltage output 10 VDC, SELV
KL3	3	GND	Reference ground for control interface, SELV
KL3	4	RSA	RS485 interface for MODBUS, RSA; SELV
KL3	5	RSB	RS485 interface for MODBUS, RSB; SELV
KL3	6	Tacho	Tach output, open collector, 1 pulse per revolution, Isink max = 10 mA, SELV

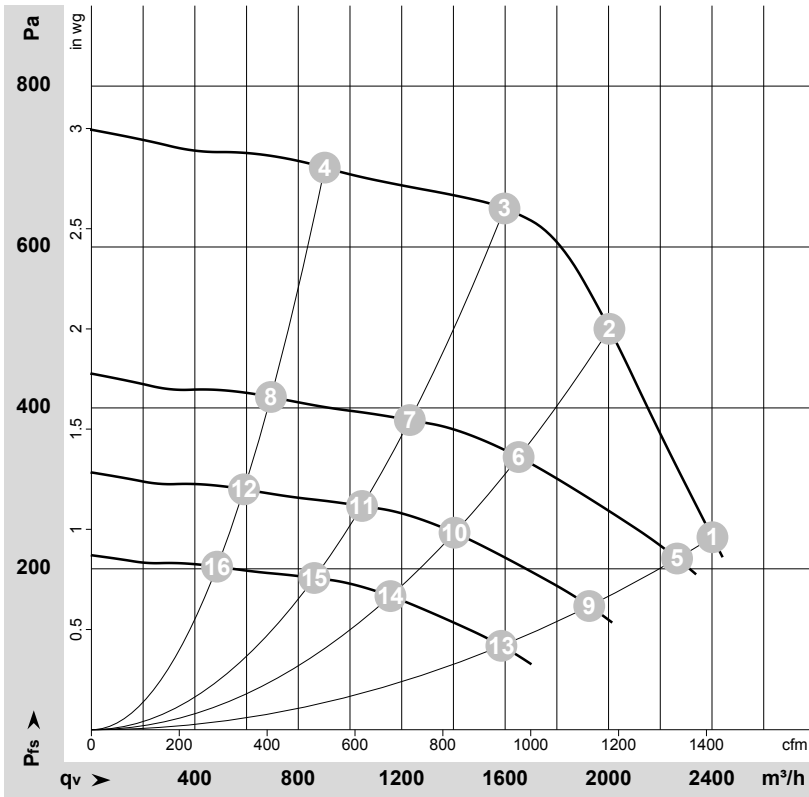


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Curves: Air performance 50 Hz



$\rho = 1.175 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-169969-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	q _v	P _{fs}	q _v	P _{fs}
		V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	Y	230	50	2110	750	3.30	72	84	2400	240	1415	0.96
2	Y	230	50	2425	750	3.30	71	83	2005	500	1180	2.01
3	Y	230	50	2600	675	2.96	71	82	1600	650	940	2.61
4	Y	230	50	2600	434	1.92	69	80	900	700	530	2.81
5	Y	230	50	2000	629	2.75	70	82	2265	216	1335	0.87
6	Y	230	50	2000	419	1.83	66	78	1650	341	970	1.37
7	Y	230	50	2000	308	1.35	64	75	1230	385	725	1.55
8	Y	230	50	2000	198	0.88	62	74	695	414	410	1.66
9	Y	230	50	1700	386	1.69	66	78	1925	156	1135	0.63
10	Y	230	50	1700	257	1.13	62	74	1405	246	825	0.99
11	Y	230	50	1700	189	0.83	60	71	1045	278	615	1.12
12	Y	230	50	1700	121	0.54	58	70	590	299	345	1.20
13	Y	230	50	1400	216	0.94	61	73	1585	106	935	0.43
14	Y	230	50	1400	144	0.63	57	69	1155	167	680	0.67
15	Y	230	50	1400	106	0.46	55	66	860	189	505	0.76
16	Y	230	50	1400	68	0.30	53	65	485	203	285	0.81

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
 q_v = Air flow · P_{fs} = Pressure increase

